



UNIVERSITAS GADJAH MADA

Faculty of Mathematics and Natural Sciences

Department of Computer Science and Electronics

Sekip Utara Bulaksumur Yogyakarta 55281 Telp: +62 274 546194 Email: depro-ika.mipa@ugm.ac.id Website: <http://dcse.fmipa.ugm.ac.id>

Bachelor in Electronics and Instrumentation

Telp : +62 274 546194

Email : kaprodi-s1-elins.mipa@ugm.ac.id

Website : <http://dcse.ugm.ac.id/>

MODULE HANDBOOK

Module name	Experiment on Actuator Systems																		
Module level	Undergraduate																		
Code	MII-2308																		
Courses (if applicable)	Experiment on Actuator Systems																		
Semester	Fall (Odd)																		
Contact person	Aufaclav Zatu Kusuma F																		
Lecturer	Aufaclav Zatu Kusuma F																		
Language	Bahasa Indonesia & English																		
Relation to curriculum	1. Undergraduate degree program, compulsory, 3th semester. 2. International undergraduate program, compulsory, 3th semester.																		
Type of teaching, contact hours	1. Undergraduate degree program: lectures, < 40 students, 2. International undergraduate program: lectures, < 30 students.																		
Workload	1. Lectures: 2 x 50 = 100 minutes (1 hours 10 menit) per week. 2. Exercises and Assignments: 2 x 50 = 100 minutes per week. 3. Private study: 2 x 50 = 100 minutes per week.																		
Credit points	2 credit points (sks).																		
Requirements according to the Examination regulations	A student must have attended at least 75% of the lectures to sit in the exams.																		
Recommended prerequisites	-																		
Learning outcomes (course outcomes) and their corresponding PLOs	<p>After completing this module, a student is expected to:</p> <p>CO1 Students are able to understand basic concepts, calibration, use actuator system</p> <p>CO2 Students are able to apply the basic concepts of the system actuator</p> <p>CO3 Students are able to solve problems and designing a system actuators in a process in the everyday environment as well as in the industry with a professional attitude</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th colspan="2">PLO</th> <th>CO1</th> <th>CO2</th> <th>CO3</th> </tr> </thead> <tbody> <tr> <td rowspan="3">Program Learning</td> <td>PLO1</td> <td></td> <td></td> <td></td> </tr> <tr> <td>PLO2</td> <td>√</td> <td></td> <td></td> </tr> <tr> <td>PLO3</td> <td></td> <td>√</td> <td></td> </tr> </tbody> </table>	PLO		CO1	CO2	CO3	Program Learning	PLO1				PLO2	√			PLO3		√	
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Contents	<ol style="list-style-type: none"> 1. Introduction to actuator 2. Signal and system 3. Motor DC 4. Motor Stepper 5. Motor Servo 6. Motor Brushless 7. Relay and Solenoid 8. Pneumatics 																																				
Study and examination requirements and forms of examination	<p>The evaluation is done in 3 forms, namely:</p> <ol style="list-style-type: none"> 1. Trial, either midterm or semester test, 2. Four tasks, individual assignments to be completed within a certain timeframe, and 3. Two quizzes, held on face-to-face, once before midterm exam and once after midterm exam, with a short answer form. <p>Assessment is done using benchmark assessment, with the aim of measuring the level of student understanding related to the target and class rank.</p>																																				
Media employed	LCD, blackboard, and websites.																																				
Assessments and Evaluation	<table border="1"> <thead> <tr> <th data-bbox="505 1146 743 1178">Type</th> <th data-bbox="743 1146 922 1178">Percentage</th> <th data-bbox="922 1146 1011 1178">√</th> <th data-bbox="1011 1146 1101 1178">√</th> <th data-bbox="1101 1146 1214 1178">√</th> </tr> </thead> <tbody> <tr> <td data-bbox="505 1178 743 1220">Quiz</td> <td data-bbox="743 1178 922 1220">5 %</td> <td data-bbox="922 1178 1011 1220">√</td> <td data-bbox="1011 1178 1101 1220">√</td> <td data-bbox="1101 1178 1214 1220">√</td> </tr> <tr> <td data-bbox="505 1220 743 1262">Individual Task</td> <td data-bbox="743 1220 922 1262">25 %</td> <td data-bbox="922 1220 1011 1262">√</td> <td data-bbox="1011 1220 1101 1262">√</td> <td data-bbox="1101 1220 1214 1262">√</td> </tr> <tr> <td data-bbox="505 1262 743 1304">Group Task</td> <td data-bbox="743 1262 922 1304">0</td> <td data-bbox="922 1262 1011 1304"></td> <td data-bbox="1011 1262 1101 1304"></td> <td data-bbox="1101 1262 1214 1304"></td> </tr> <tr> <td data-bbox="505 1304 743 1346">Midterm Exam</td> <td data-bbox="743 1304 922 1346">40 %</td> <td data-bbox="922 1304 1011 1346">√</td> <td data-bbox="1011 1304 1101 1346">√</td> <td data-bbox="1101 1304 1214 1346">√</td> </tr> <tr> <td data-bbox="505 1346 743 1388">Final Exam</td> <td data-bbox="743 1346 922 1388">30 %</td> <td data-bbox="922 1346 1011 1388">√</td> <td data-bbox="1011 1346 1101 1388">√</td> <td data-bbox="1101 1346 1214 1388">√</td> </tr> <tr> <td data-bbox="505 1388 743 1430">Total</td> <td data-bbox="743 1388 922 1430">100%</td> <td data-bbox="922 1388 1011 1430"></td> <td data-bbox="1011 1388 1101 1430"></td> <td data-bbox="1101 1388 1214 1430"></td> </tr> </tbody> </table>		Type	Percentage	√	√	√	Quiz	5 %	√	√	√	Individual Task	25 %	√	√	√	Group Task	0				Midterm Exam	40 %	√	√	√	Final Exam	30 %	√	√	√	Total	100%			
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Reading List	<ol style="list-style-type: none"> [1] Bishop, R.H., 2008, Mechatronic Systems, Sensors and Actuators, Fundamentals and Modeling, CRC Press USA [2] David G. Alciatore dan M.B. Histan, 2007, “ Introduction to Mechatronics and Measurement Systems”, McGraw-Hill, USA. [3] Hanselman, D., 2003, Brushless Permanent Magnet Motor Design, 2nd Edition The Writers' Collective [4] Yon Rijono, 1997; Dasar Teknik Tenaga Listrik, Andi Offset Yogyakarta 																																				

